DESIGN OF MULTI-MODAL SIGNAL PROGRESSION ALONG AN ARTERIAL WITH BUS DEDICATED LANES

Abstract

- In response to the increasing deployment of bus dedicated lanes in practice, this study presents a bandwidth maximization model that designs both phase sequences and offsets over a series of intersections along an arterial with bus dedicated lanes to provide concurrent progression for bus and general traffic flows.
- The proposed model takes into account the following factors that may affect the progression effectiveness:
 - bus dwelling time at bus stops
 - location of bus dedicated lanes
 - traffic queues; and
 - conflicts between through bus movements and leftturning traffic.
- The results from numerical analysis with two planned BRT sites have confirmed the effectiveness of the proposed model and the evaluation with extensive simulation experiments has verified the benefits from concurrent progression.

Case Study





Case 2: Dedicated Median BUS Lanes

- Bus Schedule SB: 2 bus/1min, NB: 2 bus/1min
- Dwell Time: SB-15sec, NB-15sec







by Hyeonmi Kim¹, Yao Cheng², and Gang-Len Chang²

Modelling Methodology

Travel Time Difference between Buses and PCs

• A bus may take a longer travel time than a passenger car over the same arterial link due to the larger size and the lower cruising speed. • Such differences may be more pronounced if a bus dwells at a bus stop \rightarrow deviates away from the progression band designed for passenger cars \rightarrow encounters a red phase at the downstream intersection.

Conflicts between Buses on Dedicated Bus Lanes and Turning PCs

• Dedicated bus lanes are used to reduce interactions between bus and passenger cars and improve bus operations.

• If median dedicated bus lanes, there exist conflicts between buses on the dedicated bus lanes and left-turning passenger cars in the same direction, which in turn impact the effectiveness of signal phases allocated for both modes.

Traffic Queues on Bus Dedicated Lanes

• To prevent an interruption on buses travelling in the progression band, traffic queues at downstream intersections on the bus dedicated lanes need to be discharged before the following buses arrive. • Depending on the position of bus dedicated lanes, those traffic queues

may compose of different sets of vehicles • Bus dedicated lanes in the median: with the unsynchronized buses

• Bus dedicated lanes on the curb: with both the unsynchronized buses and right-turning vehicles sharing the right-of-way

Selecting the Mode and Direction for Progression Design

• One needs to select the mode and direction to receive the progression bands, based on traffic volumes and loading factors of passenger cars and buses, as well as the design of bus dedicated lanes.











Optimization Results

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section 1 2 3	Left-Turn Phase Patterns	Offset (s)		BAND	The Propose	d Model	Intersection	Phase Patterns	Offset (s)	Phase Patterns	Offset (s)	Phase Patterns	Offse t (s)
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3		25		113		113	4	OB Left Lag	52	OB Left Lag	124	OB/IB Left	93
Δ	IB Left	113	IB Left	59	IB Left	71		/IB Left Lead		/IB Left Lead		Lead	
	leading	104	leading	39	leading	29	5	OB Left Lag	116	OB Left Lag	38	OB/IB Left	9
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<Signal progression plan generated with MAXBAND and the proposed model>

1. The Korea Transport Institute 2. The University of Maryland, College Park



Objective Function	Green Time for Passenge	r Cars and	Buses	
\sum^{N} $\sum^{N-1} \overline{\overline{\overline{x}}} = \sum^{N-1} \overline{\overline{\overline{x}}} =$	$g_{c,i} = 1 - (R_i + L_i)$ $\bar{a} = 1 - (R_i + L_i)$			
$\max \sum_{i=1+1}^{b_{c}} v_{c,i} K_{c} + \sum_{i=1}^{b_{c}} v_{c,i} K_{c} + (N-1) b_{b} V_{b} K_{b} + (N-1) b_{b} V_{b} K_{b}$	$g_{c,i} - I - (K_i + L_i)$ $(1 (D + \overline{L} + L_i))$	if & 1 &	_ 1	
	$g_{b,i} = \begin{cases} 1 - (R_i + L_i + L_i * y) \\ 1 - (R_i + \max(\overline{L_i} + L_i * y)) \end{cases}$	$r = \frac{1}{\delta} \frac{1}{\delta} \frac{1}{\delta} \frac{1}{\delta}$	i — ⊥	
Constraints for Progression Bands for Passenger Cars	$(\mathbf{I} (\mathbf{R}_{1} + \mathbf{I}) \mathbf{R}_{2} \mathbf{R}_{1})$	()) (0) (0)		
$0 \le w_{c,i} + b_c \le g_{c,i} \qquad \qquad 0 \le \overline{w}_{c,i} + \overline{b}_c \le \overline{g}_{c,i}$	$\overline{g}_{hi} = \begin{cases} 1 - (R_i + L_i + \overline{L}_i * y) \\ - \overline{L}_i & - \overline{L}_i \end{cases}$	if $\delta_i + \overline{\delta}$	_i = 1	
$\theta_{i} + w_{c,i} + t_{c,i} + n_{c,i} \ge \theta_{i+1} + w_{c,i+1} + n_{c,i+1} - M(1 - x_{c})$	$1 - (R_i + max(L_i, L_i * y))$	$(v))$ if $\delta_i + \delta_j$	_i ≠ 1	
$\theta_{i} + w_{c,i} + t_{c,i} + n_{c,i} \le \theta_{i+1} + w_{c,i+1} + n_{c,i+1} + M(1 - x_{c})$	Traffic Queue and Bay Ler	ngth Const	raints	
$-\theta_{i} + r_{c,i} + R_{c,i} + w_{c,i} + t_{c,i} + n_{c,i} \ge -\theta_{i+1} + r_{c,i+1} + R_{c,i+1} + w_{c,i+1} + n_{c,i+1} - M(1 - x_{c})$	$1^{b} - V (\sigma \min(\theta) + \sigma)$	• +		t Ω))
$-\theta_{i} + r_{c,i} + \overline{R}_{c,i} + \overline{w}_{c,i} + \overline{t}_{c,i} + \overline{n}_{c,i} \le -\theta_{i+1} + r_{c,i+1} + \overline{R}_{c,i+1} + \overline{w}_{c,i+1} + \overline{n}_{c,i+1} + M(1 - \overline{x}_{c})$	$I_i - V_b (g_{b,i-1} - \min(O_{i-1} + g))$	b,i-1 + b,i-1	$- v_i, v_i + g_{b,i}$	$-v_{b,i-1} - v_{i-1}$
$b_c \le x_c$ $\overline{b}_c \le \overline{x}_c$	$\overline{l}_{i}^{b} = \overline{V}_{b} \left(\overline{g}_{b,i+1} - \min(\theta_{i+1} + \overline{g}) \right)$	$b_{i+1} + \overline{t}_{b,i} - $	$\theta_i, \theta_i + \overline{g}_{b,i+1} -$	$-\overline{t}_{b,i} - \overline{\theta}_{i+1})\Big)$
Constraints for Progression Bands for Buses	$\frac{l_{i}^{b}}{s}(1 + \frac{V_{b}}{s}) \le w_{b,i} + M(1 - x_{b})$			
$0 \le w_{b,i} + b_b \le g_{b,i} \qquad 0 \le \overline{w}_{b,i} + \overline{b}_b \le \overline{g}_{b,i}$	$\frac{\overline{l}_{i}^{b}}{c}\left(1+\frac{\overline{V}_{b}}{c}\right) \leq \overline{g}_{b,i} - \overline{b}_{b} - \overline{w}_{b,i} + \frac{\overline{V}_{b}}{c} = \overline{V}_{b,i} + \frac{\overline{V}_{b}}{c} =$	$M(1-\overline{x}_b)$		
$\theta_{i} + w_{b,i} + t_{b,i} + n_{b,i} \ge \theta_{i+1} + w_{b,i+1} + n_{b,i+1} - M(1 - x_{b})$	$l_i^r = f_i^r (1 - g_{c,i}) \qquad \overline{l}_i^r$	$\bar{f} = \bar{f}_i^r (1 - \bar{g}_c)$,i)	
$\Theta_{i} + W_{b,i} + \tau_{b,i} + n_{b,i} \le \Theta_{i+1} + W_{b,i+1} + n_{b,i+1} + M(1 - x_{b})$	$l_i^b + l_i^r$ $V_b + f_i^r$) I M		
$-\theta_{i} + r_{b,i} + \frac{R_{b,i}}{L} + \overline{w}_{b,i} + t_{b,i} + \overline{n}_{b,i} \ge -\theta_{i+1} + r_{b,i} + \frac{R_{b,i}}{L} + \overline{w}_{b,i+1} + \overline{n}_{b,i+1} - M(1 - \overline{x}_{b})$	$\frac{1}{s} (1 + \frac{1}{s}) \leq W_{b,i} + M(1 + \frac{1}{s})$	$-x_b$) + My		
$-\theta_{i} + r_{b,i} + \overline{R}_{b,i} + \overline{w}_{b,i} + \overline{t}_{b,i} + \overline{n}_{b,i} \le -\theta_{i+1} + r_{b,i} + \overline{R}_{b,i} + \overline{w}_{b,i+1} + \overline{n}_{b,i+1} + M(1 - \overline{x}_{b})$	$\frac{\overline{l}_{i}^{b} + \overline{l}_{i}^{r}}{c} \left(1 + \frac{\overline{V}_{b} + \overline{f}_{i}^{r}}{c}\right) \leq \overline{g}_{b,i} - \overline{b}_{b} - \overline{v}$	$\overline{w}_{b,i} + M(1 - $	$(\overline{x}_b) + My$	
$b_b \le x_b$ $b_b \le x_b$	5 5	* OB: outbound, IB	: inbound. Each pattern is	shown in the figure left.
			r	
Difference in the Starting Times of Green Phases between Inbound	Left Turn Phase Patterns*	r _{c,i}	$\mathbf{y} = 0$	y = 1
and Outbound Through Movements	1 OB Left Leads, IB Lags	$-L_i$	-L _i	0
		.	,	

 $\mathbf{r}_{c,i} = (\delta_i - 1)\mathbf{L}_i - (\delta_i - 1)\mathbf{L}_i$ $\mathbf{r}_{\mathrm{b},\mathrm{i}} = (\delta_{\mathrm{i}} - 1)\mathbf{L}_{\mathrm{i}} - (\overline{\delta}_{\mathrm{i}} - 1)\overline{\mathbf{L}}_{\mathrm{i}} + (\overline{\delta}_{\mathrm{i}} - 1)\overline{\mathbf{L}}_{\mathrm{i}}\mathbf{y} - (\delta_{\mathrm{i}} - 1)\mathbf{L}_{\mathrm{i}}\mathbf{y}$

Simulation Results

Control delay for passenger car and bus flows

100 90 80 70 60 50 40 30 20 10 0	Car	Case 1	80 70 60 50 40 30 20 10 0	Car	
TRANSYT7F	62.7	87.2	TRANSYT7F	73.5	3
MAXBAND	57.0	60.5		56.1	3
Proposed Model	46.3	45.1	Proposed Model	47.9	1
TRA	NSYT7F 🗆 MAXBAND 🖾	Proposed Model		SYT7F 🗆 MAXBAND 🔳	Proposed Mod

✤ Average Person Delay

	Case 1	Case 2
TRANSYT 7F	69.3	54.3
MAXBAND	57.9	46.5
The proposed Model	46.0	33.2

* Loading factors: passenger car (1.2) and buses (35)

Percent Change in Average Person Delay compared to MAXBAND

		Case 1		Case 2			
Loading Factor		Passen	ger Car	Passenger Car			
		1.2	1.5	1.2	1		
	30	-20.5%	-20.2%	-27.7%	-25		
Bus	35	-20.7%*	-20.4%	-29.2%*	-27		
	40	-20.8%	-20.5%	-30.5%	-28		
* Base scenario of loading factors: passenger car(1.2) and bus(35)							

•	Number of stops for passenger car and bus flows					
		Case 1		Case 2		
		PC	Bus	PC	В	
	TRANSYT7F	3.7	4.1	2.2	1	
	MAXBAND	3.6	3.7	1.9	2	
	The proposed Model	2.5	2.7	1.5	1	





Model Formulation

Loft Turn Dhaco Dattorns*		1 4	* D,1		
Lei	t Turn Phase Patterns	C,i	$\mathbf{y} = 0$	y = 1	
1	OB Left Leads, IB Lags	$-L_i$	$-L_i$	0	
2	OB Left Lags, IB Leads	\overline{L}_i	\overline{L}_{i}	0	
3	OB and IB Left Leads	$-L_i + \overline{L}_i$	$-L_i + \overline{L}_i$	0	
4	OB and IB Left Lags	0	0	0	

Conclusions

- Case 2 del
- (in seconds/person)

 - .1% 3.3%

- This study has developed a signal optimization model to provide concurrent progression to passenger cars and buses along an arterial with dedicated bus lanes.
- The proposed model computes the optimal phase sequences and offsets that maximize the total benefit of all arterial users under various geometric conditions and leftturn phase patterns.
- The model takes into account the difference in travel times between passenger cars and buses, conflicts between buses on dedicated bus lanes and turning vehicles, and relations between bus stop locations and traffic queues.
- The comparison results from the extensive simulation experiments show that the proposed model can outperform other arterial signal design models in terms of control delays for buses, the number of stops for buses, and average person delay, compared to MAXBAND and TRANSYT7F.
- With such a signal system, responsible traffic agencies can minimize the resistance from passenger car users when promoting and facilitating the use of transit system.
- Further research: incorporating an active TSP in the design, developing a rigorous yet robust model for the selection of its deployment location and accounting for potential variance in the available input data.